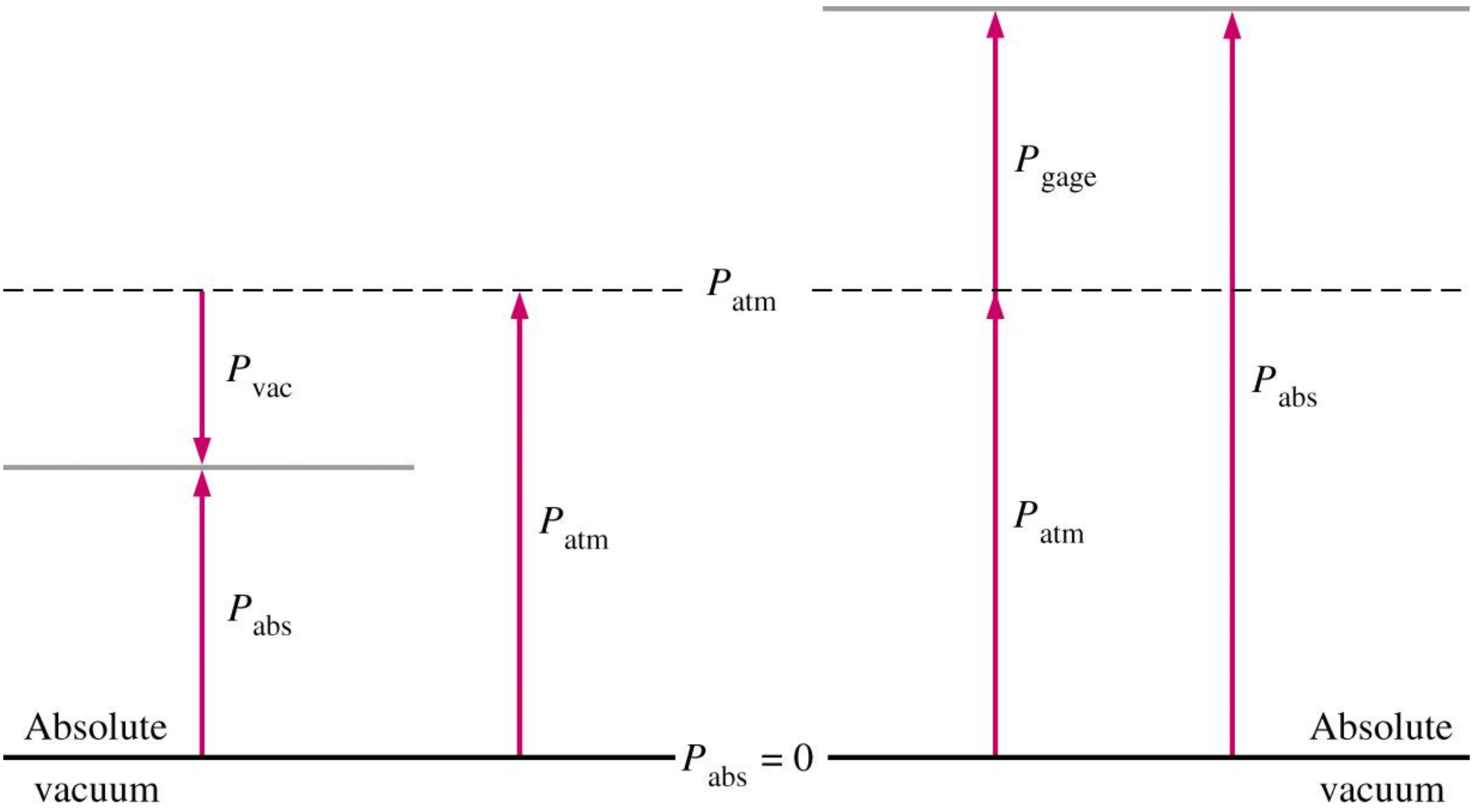
Pressure

- **Pressure** is defined as a *normal force exerted by a fluid per unit area*.
- Units of pressure are N/m^2, which is called a **pascal** (Pa).
- Since the unit Pa is too small for pressures encountered in practice, *kilopascal* (1 kPa = 10^3 Pa) and *megapascal* (1 MPa = 10^6 Pa) are commonly used.
- Other units include *bar*, *atm, kgf/cm^2, lbf/in^2=psi*.

Absolute, gage, and vacuum pressures

- Actual pressure at a give point is called the **absolute pressure**.
- Most pressure-measuring devices are calibrated to read zero in the atmosphere, and therefore indicate **gage pressure**, $P_{gage}=P_{abs} - P_{atm}$.
- Pressure below atmospheric pressure are called **vacuum pressure**, $P_{vac}=P_{atm} - P_{abs}$.

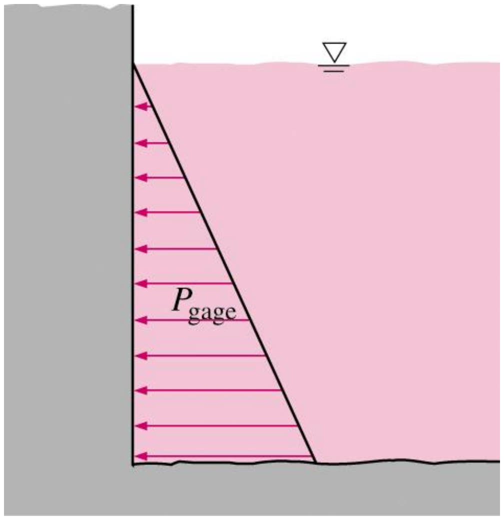
Absolute, gage, and vacuum pressures

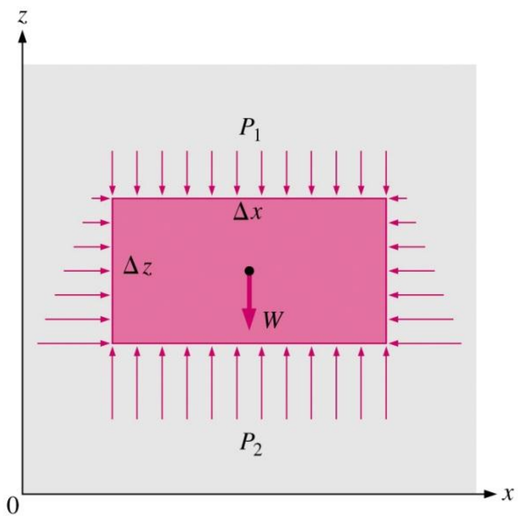


Pressure at a Point

- Pressure at a any point in a fluid is the same in all directions.
- Pressure has a magnitude, but not a specific direction, and thus it is a scalar quantity.
- Proof on blackboard.

Variation of Pressure with Depth





- In the presence of a gravitational field, pressure increases with depth because more fluid rests on deeper layers.
- To obtain a relation for the variation of pressure with depth, consider rectangular element
  - Force balance in *z*-direction gives

$$\sum F_z = m a_z = 0$$

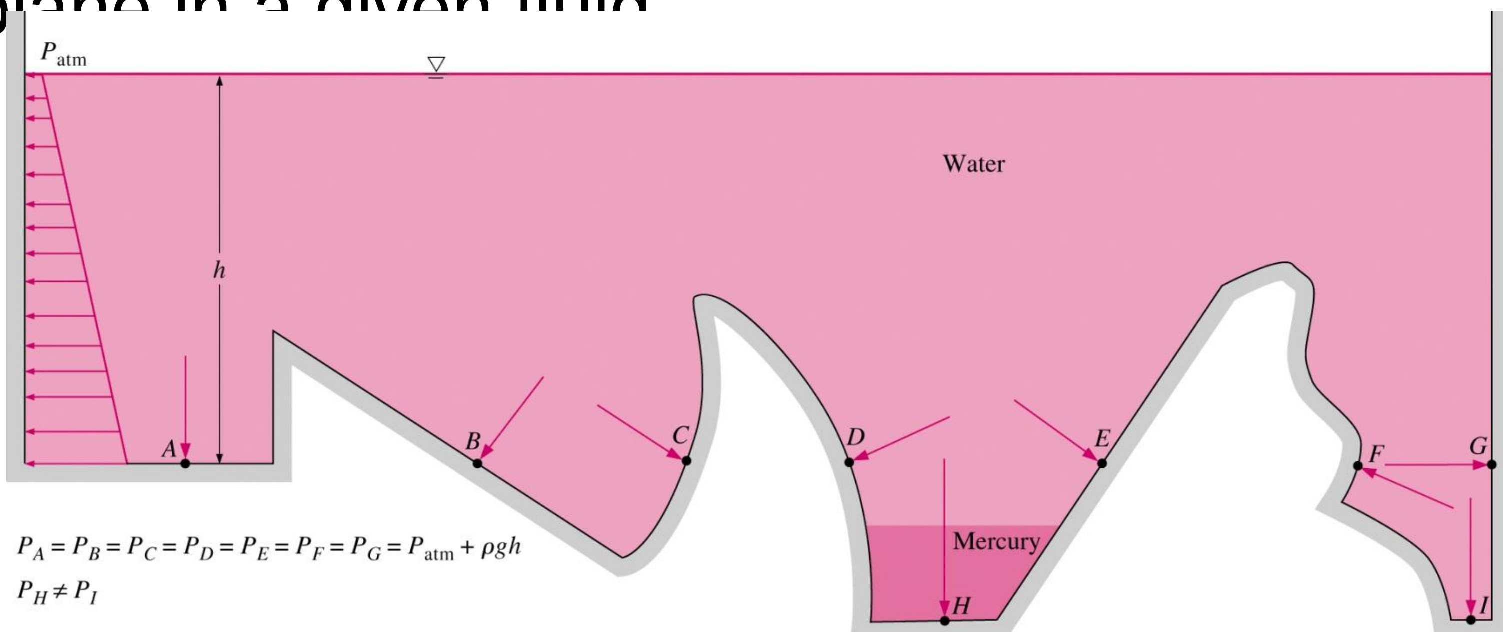
$$P_2 \Delta x - P_1 \Delta x - \rho g \Delta x \Delta z = 0$$

  - Dividing by Δx and rearranging gives

$$\Delta P = P_2 - P_1 = \rho g \Delta z = \gamma_s \Delta z$$

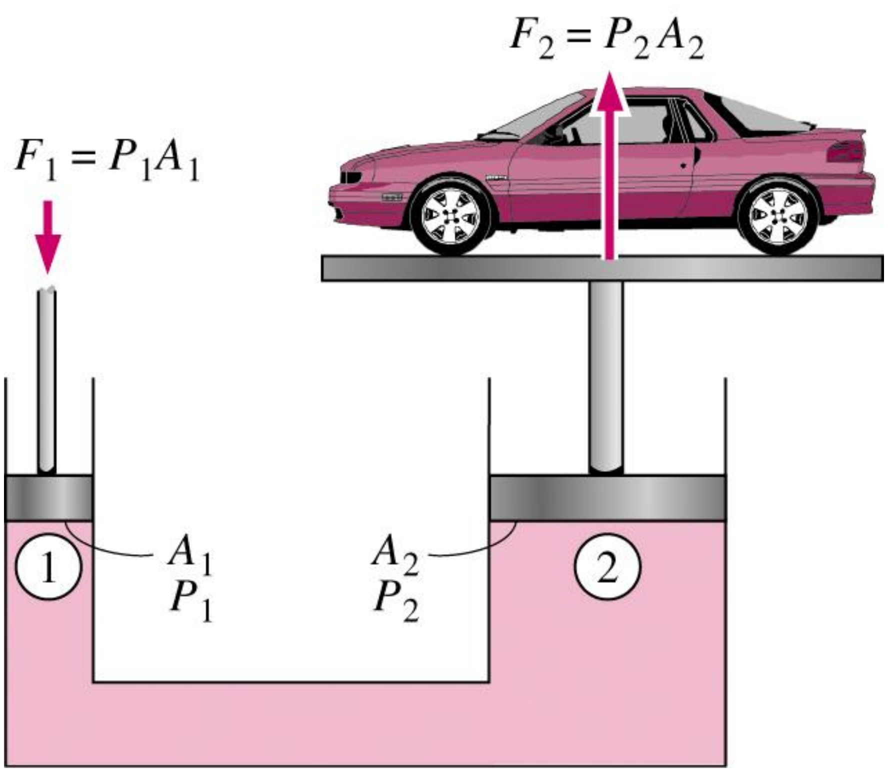
Variation of Pressure with Depth

- Pressure in a fluid at rest is independent of the shape of the container.
- Pressure is the same at all points on a horizontal plane in a given fluid.



Scuba Diving and Hydrostatic Pressure

Pascal's Law

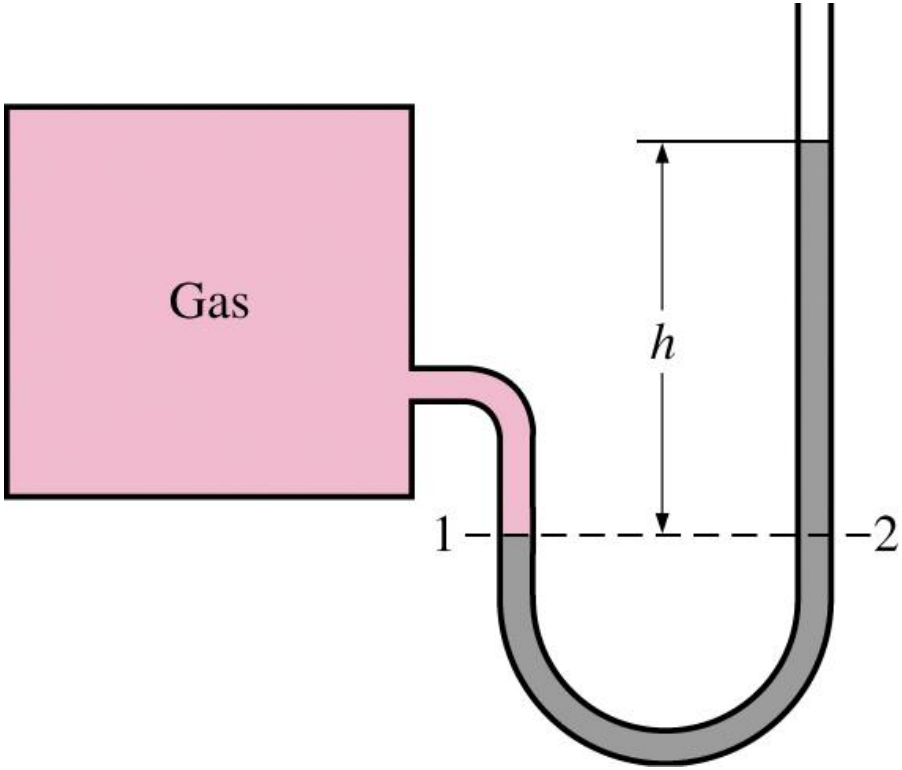


- Pressure applied to a confined fluid increases the pressure throughout by the same amount.
- In picture, pistons are at same height:

$$P_1 = P_2 \rightarrow \frac{F_1}{A_1} = \frac{F_2}{A_2} \rightarrow \frac{F_2}{F_1} = \frac{A_2}{A_1}$$

- Ratio A_2/A_1 is called *ideal mechanical advantage*

The Manometer

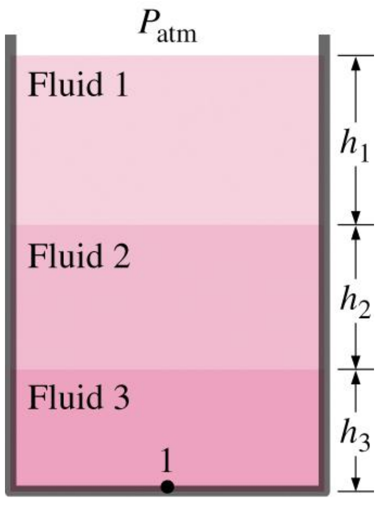


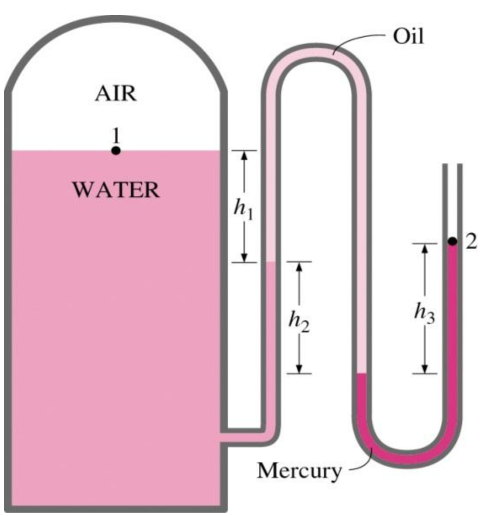
$$P_1 = P_2$$

$$P_2 = P_{atm} + \rho g h$$

- An elevation change of Δz in a fluid at rest corresponds to $\Delta P/\rho g$.
- A device based on this is called a **manometer.**
- A manometer consists of a U-tube containing one or more fluids such as mercury, water, alcohol, or oil.
- Heavy fluids such as mercury are used if large pressure differences are anticipated.

Mutlifluid Manometer

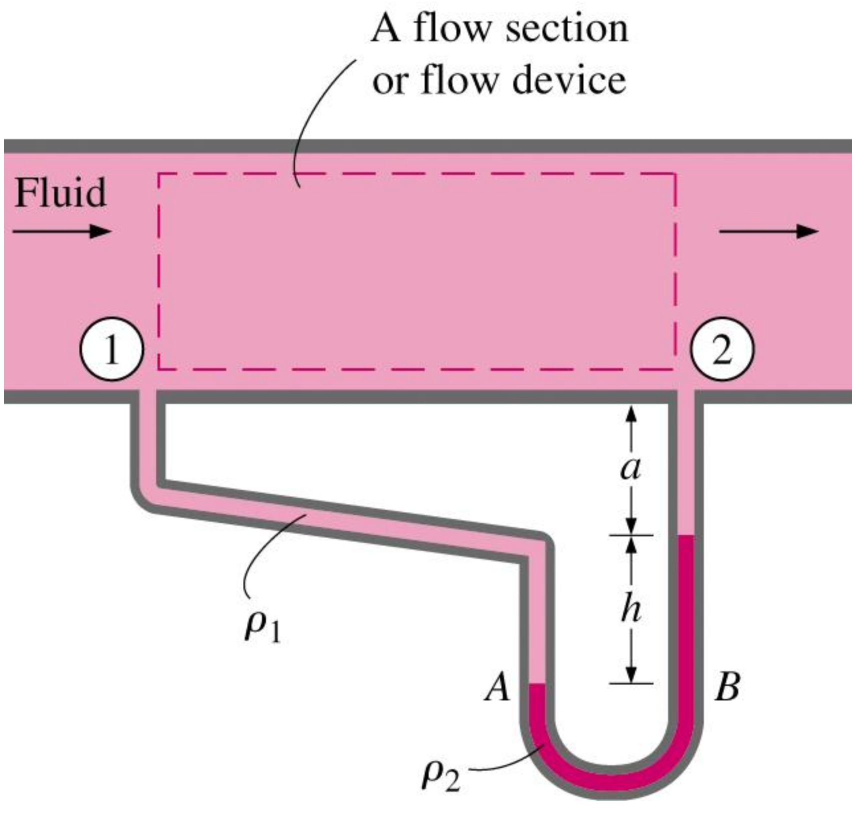




- For multi-fluid systems
  - Pressure change across a fluid column of height *h* is $\Delta P = \rho gh$.
  - Pressure increases downward, and decreases upward.
  - Two points at the same elevation in a continuous fluid are at the same pressure.
  - Pressure can be determined by adding and subtracting ρgh terms.

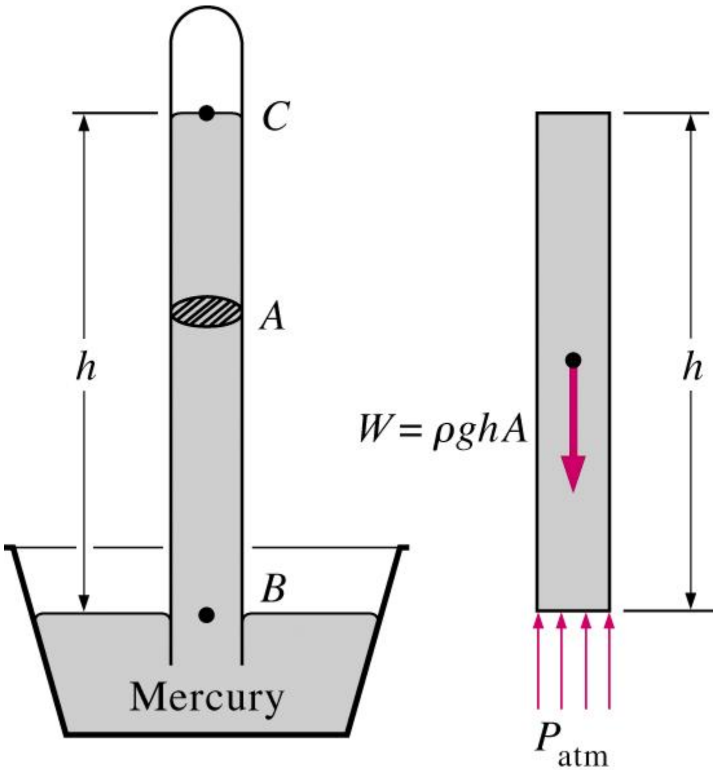
$$P_2 + \rho_1 g h_1 + \rho_2 g h_2 + \rho_3 g h_3 = P_1$$

Measuring Pressure Drops



- Manometers are well--suited to measure pressure drops across valves, pipes, heat exchangers, etc.
- Relation for pressure drop P_1-P_2 is obtained by starting at point 1 and adding or subtracting ρgh terms until we reach point 2.
- If fluid in pipe is a gas, $\rho_2 >> \rho_1$ and P_1-P_2= ρgh

The Barometer



$$P_C + \rho g h = P_{atm}$$

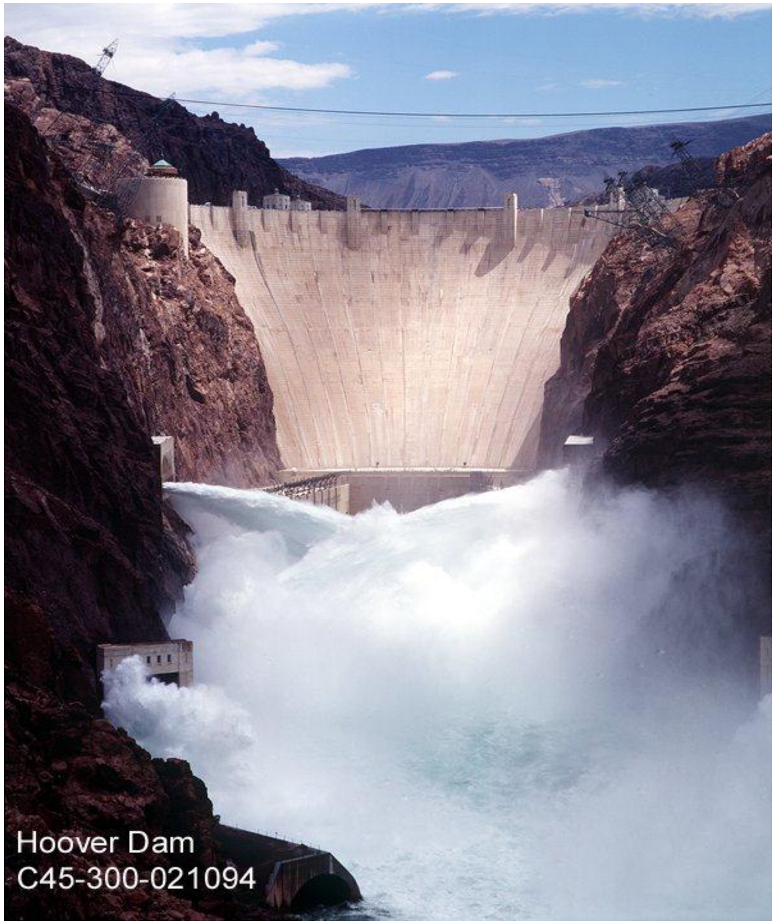
$$P_{atm} = \rho g h$$

- Atmospheric pressure is measured by a deviced called a **barometer**; thus, atmospheric pressure is often referred to as the *barometric pressure*.
- P_C can be taken to be zero since there is only Hg vapor above point C, and it is very low relative to P_{atm}.
- Change in atmospheric pressure due to elevation has many effects: Cooking, nose bleeds, engine performance, aircraft performance.

Fluid Statics

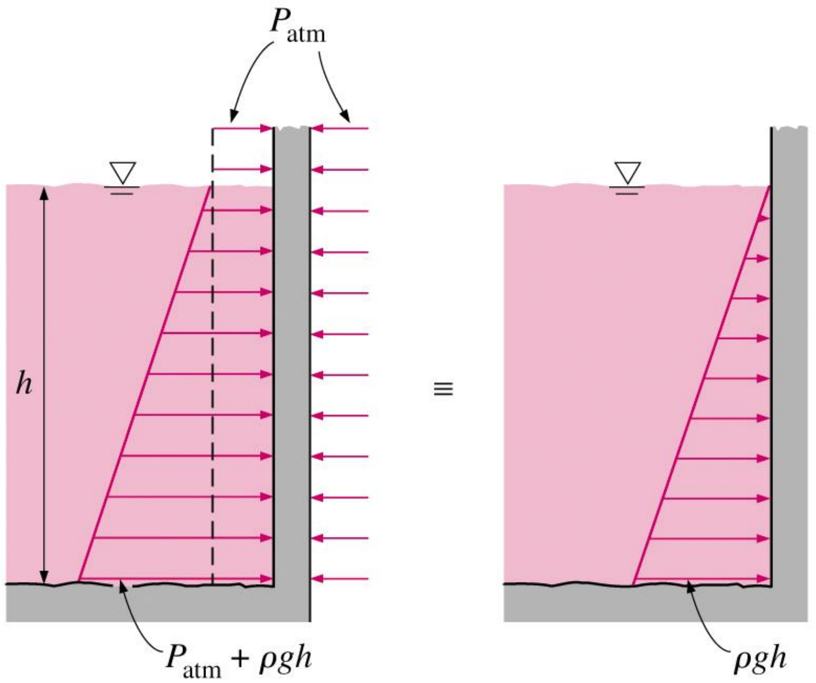
- **Fluid Statics** deals with problems associated with fluids at rest.
- In fluid statics, there is no relative motion between adjacent fluid layers.
- Therefore, there is no shear stress in the fluid trying to deform it.
- The only stress in fluid statics is *normal stress*
  - Normal stress is due to pressure
  - Variation of pressure is due only to the weight of the fluid → fluid statics is only relevant in presence of gravity fields.
- Applications: Floating or submerged bodies, water dams and gates, liquid storage tanks, etc.

Hoover Dam



- Example of elevation head *z* converted to velocity head $V^2/2g$. We'll discuss this in more detail in Lecture (Bernoulli equation).

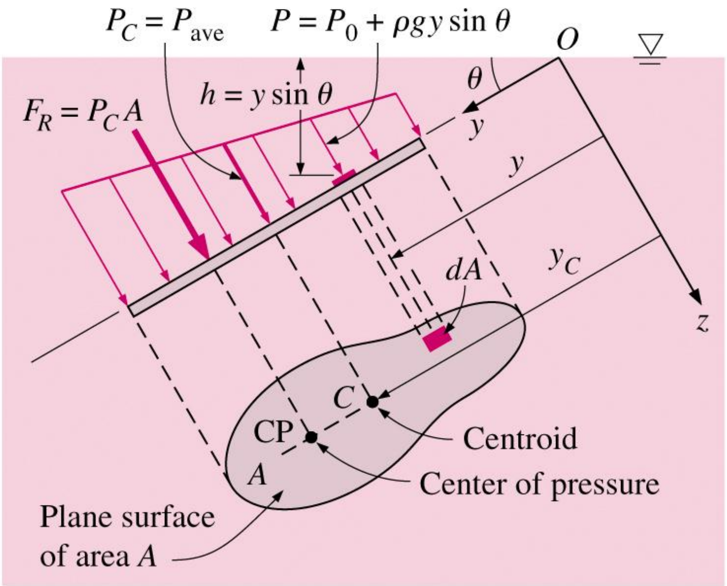
Hydrostatic Forces on Plane Surfaces

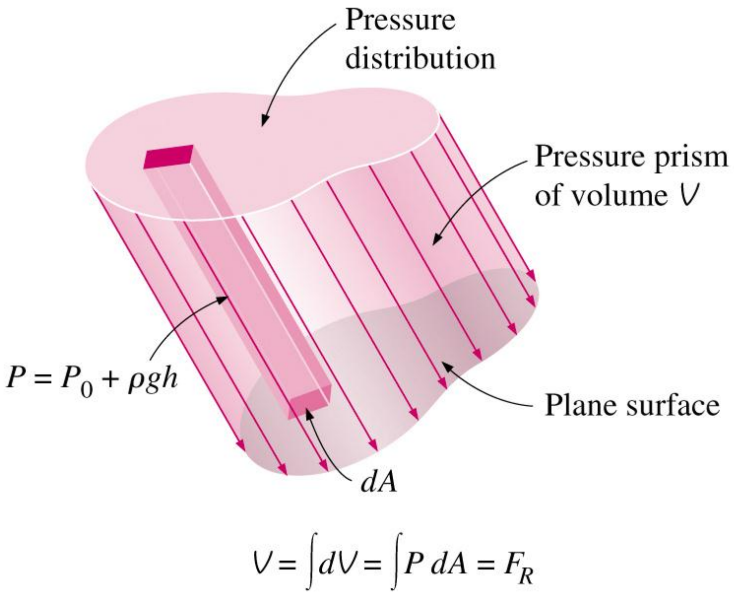


(a) P_{atm} considered (b) P_{atm} subtracted

- On a *plane* surface, the hydrostatic forces form a system of parallel forces
- For many applications, magnitude and location of application, which is called **center of pressure**, must be determined.
- Atmospheric pressure P_{atm} can be neglected when it acts on both sides of the surface.

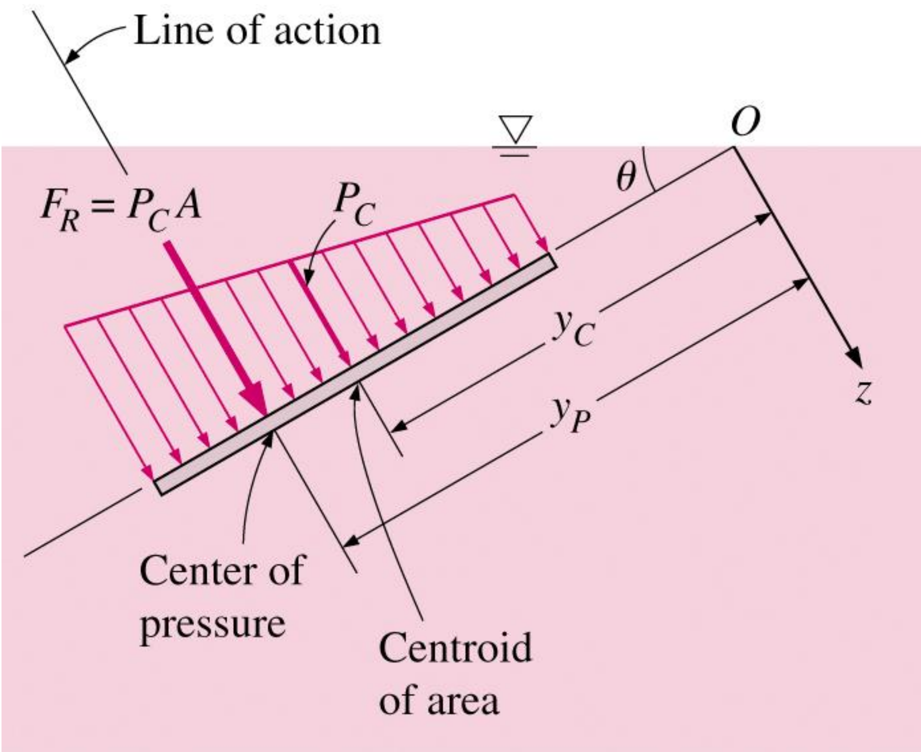
Resultant Force





The magnitude of F_R acting on a plane surface of a completely submerged plate in a homogenous fluid is equal to the product of the pressure P_C at the centroid of the surface and the area A of the surface

Center of Pressure

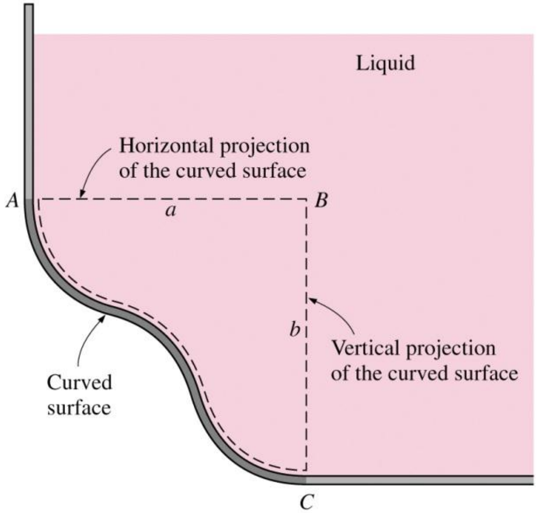


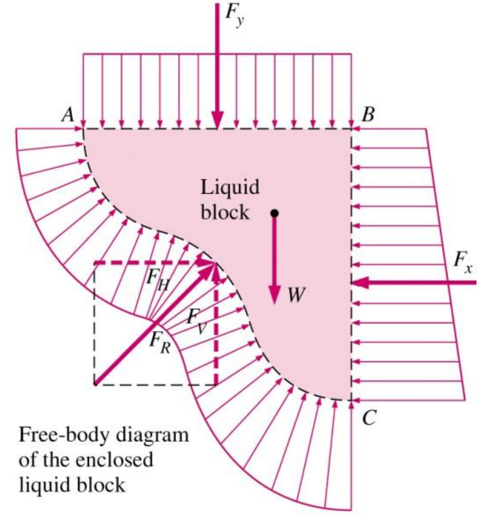
- Line of action of resultant force $F_R = P_C A$ does not pass through the centroid of the surface. In general, it lies underneath where the pressure is higher.
- Vertical location of **Center of Pressure** is determined by equation the moment of the resultant force to the moment of the distributed pressure force.

$$y_p = y_C + \frac{I_{xx,C}}{y_c A}$$

- $I_{xx,C}$ is tabulated for simple geometries.
- Derivation of F_R and examples on blackboard

Hydrostatic Forces on Curved Surfaces





- F_R on a curved surface is more involved since it requires integration of the pressure forces that change direction along the surface.
- Easiest approach: determine horizontal and vertical components F_H and F_V separately.

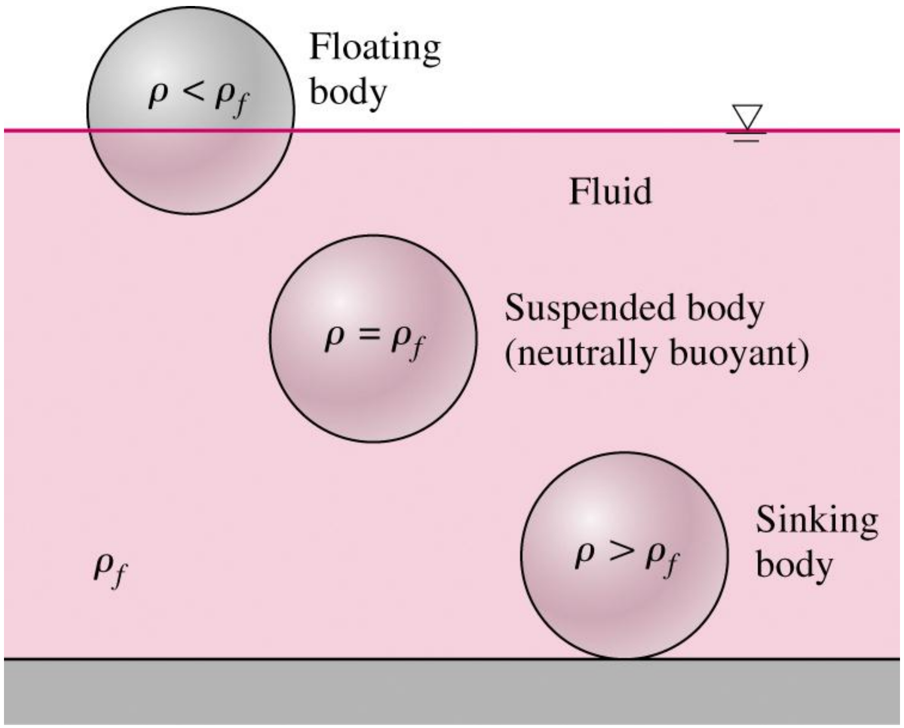
Hydrostatic Forces on Curved Surfaces

- Horizontal force component on curved surface: $F_H = F_x$. Line of action on vertical plane gives y coordinate of center of pressure on curved surface.
- Vertical force component on curved surface: $F_V = F_y + W$, where W is the weight of the liquid in the enclosed block $W = \rho g V$. x coordinate of the center of pressure is a combination of line of action on horizontal plane (centroid of area) and line of action through volume (centroid of volume).
- Magnitude of force $F_R = (F_H^2 + F_V^2)^{1/2}$
- Angle of force is $\alpha = \tan^{-1}(F_V / F_H)$

Buoyancy and Stability

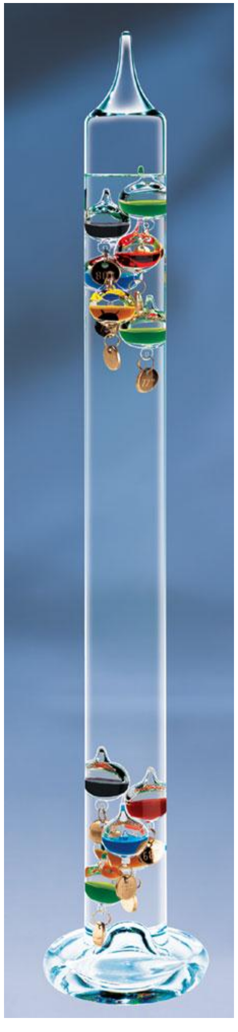
- Buoyancy is due to the fluid displaced by a body. $F_B=\rho_f gV$.
- **Archimedes principal** : The buoyant force acting on a body immersed in a fluid is equal to the weight of the fluid displaced by the body, and it acts upward through the centroid of the displaced volume.

Buoyancy and Stability



- Buoyancy force F_B is equal only to the displaced volume $\rho_f g V_{displaced}$.
- Three scenarios possible
  1. $\rho_{body} < \rho_{fluid}$: Floating body
  2. $\rho_{body} = \rho_{fluid}$: Neutrally buoyant
  3. $\rho_{body} > \rho_{fluid}$: Sinking body

Example: Galilean Thermometer



- Galileo's thermometer is made of a sealed glass cylinder containing a clear liquid.
- Suspended in the liquid are a number of weights, which are sealed glass containers with colored liquid for an attractive effect.
- As the liquid changes temperature it changes density and the suspended weights rise and fall to stay at the position where their density is equal to that of the surrounding liquid.
- If the weights differ by a very small amount and ordered such that the least dense is at the top and most dense at the bottom they can form a temperature scale.

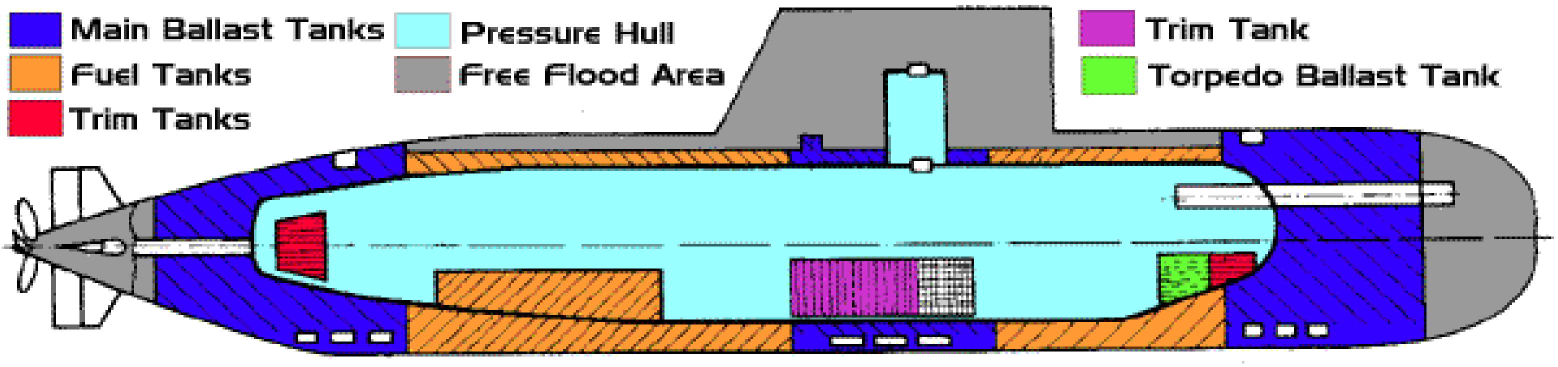
Example: Floating Drydock

Auxiliary Floating Dry Dock Resolute (AFDM-10) partially submerged

Submarine undergoing repair work on board the AFDM-10

Using buoyancy, a submarine with a displacement of 6,000 tons can be lifted!

Example: Submarine Buoyancy and Ballast



- Submarines use both static and dynamic depth control. Static control uses ballast tanks between the pressure hull and the outer hull. Dynamic control uses the bow and stern planes to generate trim forces.

Example: Submarine Buoyancy and Ballast

Normal surface trim

SSN 711 nose down after accident which damaged fore balast tanks

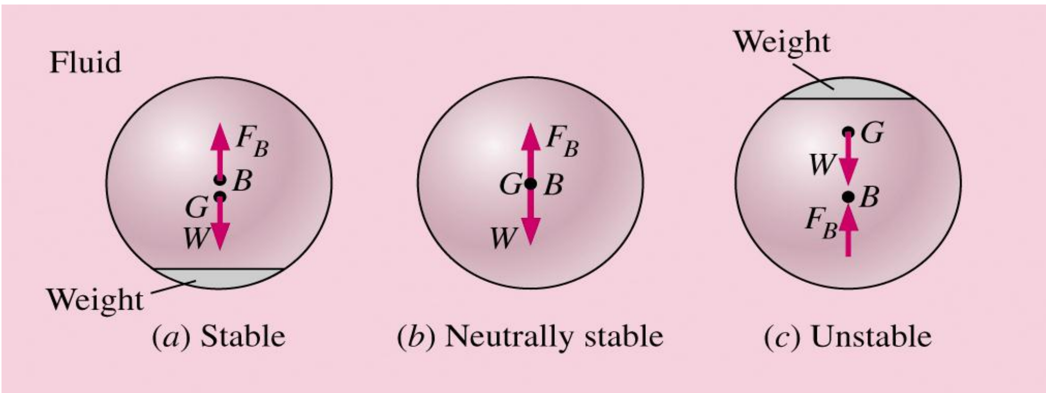
Example: Submarine Buoyancy and Ballast

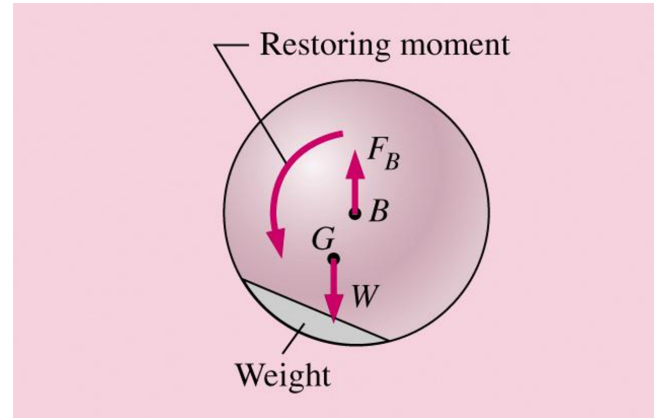
Damage to SSN 711 (USS San Francisco) after running aground on 8 January 2005.

Example: Submarine Buoyancy and Ballast

Ballast Control Panel: Important station for controlling depth of submarine

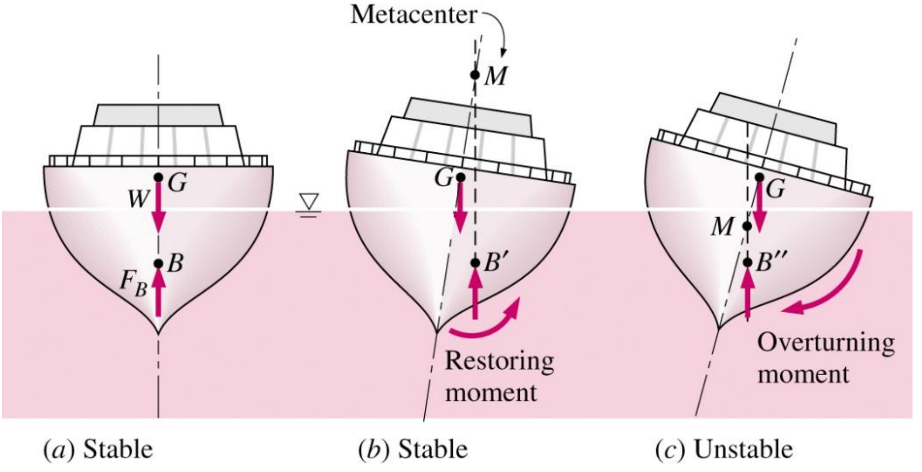
Stability of Immersed Bodies





- Rotational stability of immersed bodies depends upon relative location of *center of gravity G* and *center of buoyancy B*.
  - *G* below *B*: stable
  - *G* above *B*: unstable
  - *G* coincides with *B*: neutrally stable.

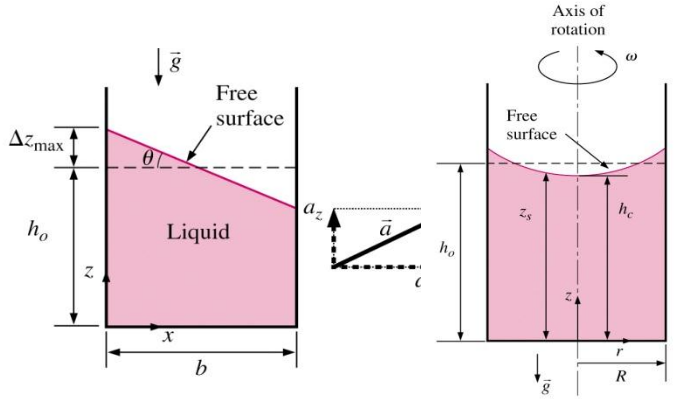
Stability of Floating Bodies



- If body is bottom heavy (*G* lower than *B*), it is always stable.
- Floating bodies can be stable when *G* is higher than *B* due to shift in location of center buoyancy and creation of restoring moment.
- Measure of stability is the metacentric height G*M*. If *GM*>1, ship is stable.

Rigid-Body Motion

- There are special cases where a body of fluid can undergo rigid-body motion: linear acceleration, and rotation of a cylindrical container.



- In these cases, no shear is developed.
- Newton's 2nd law of motion can be used to derive an **equation of motion** for a fluid that acts as a rigid body

$$\nabla P + \rho g \vec{k} = -\rho \vec{a}$$

- In Cartesian coordinates:

$$\frac{\partial P}{\partial x} = -\rho a_x, \frac{\partial P}{\partial y} = -\rho a_y, \frac{\partial P}{\partial z} = -\rho \left(g + a_x \right)$$

Linear Acceleration

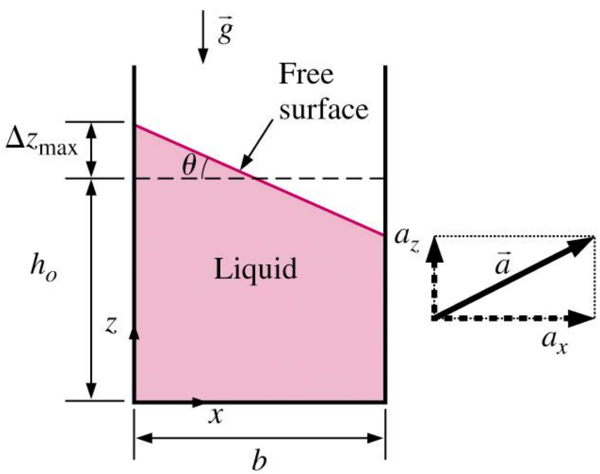
Container is moving on a straight path

$$a_x \neq 0, a_y = a_z = 0$$

$$\frac{\partial P}{\partial x} = \rho a_x, \frac{\partial P}{\partial y} = 0, \frac{\partial P}{\partial z} = -\rho g$$

Total differential of P

$$dP = -\rho a_x dx - \rho g dz$$



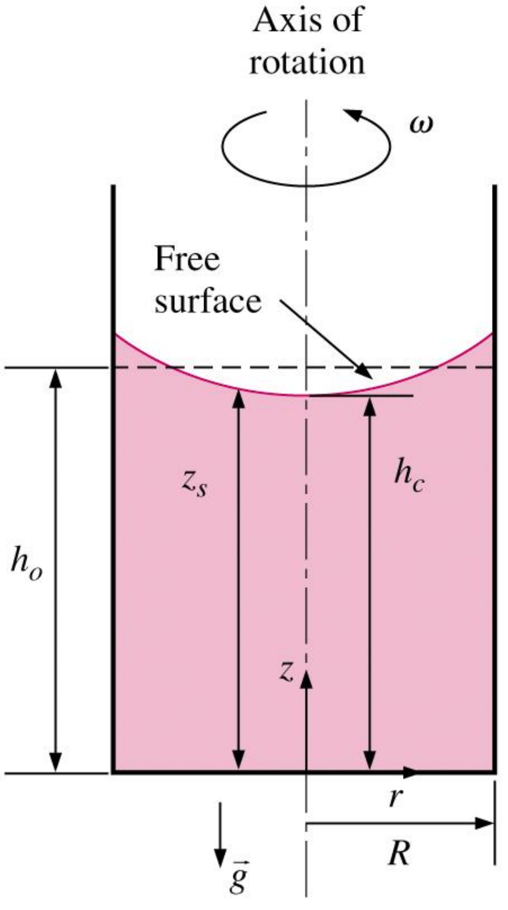
Pressure difference between 2 points

$$P_2 - P_1 = -\rho a_x (x_2 - x_1) - \rho g (z_2 - z_1)$$

Find the rise by selecting 2 points on free surface $P_2 = P_1$

$$\Delta z_s = z_{s2} - z_{s1} = -\frac{a_x}{g}(x_2 - x_1)$$

Rotation in a Cylindrical Container



Container is rotating about the z-axis

$$a_r = -r\omega^2, a_\theta = a_z = 0$$

$$\frac{\partial P}{\partial r} = \rho r \omega^2, \frac{\partial P}{\partial \theta} = 0, \frac{\partial P}{\partial z} = -\rho g$$

Total differential of P

$$dP = \rho r \omega^2 dr - \rho g dz$$

On an isobar, dP = 0

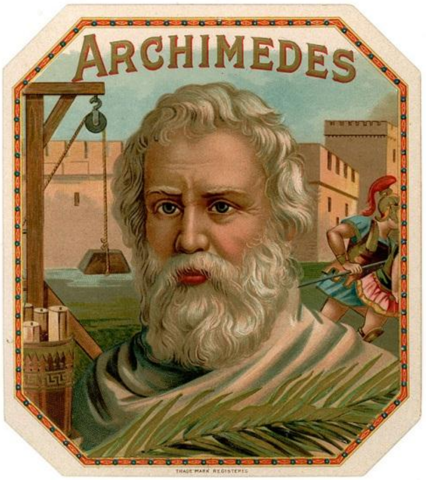
$$\frac{dz_{isobar}}{dr} = \frac{r\omega^2}{g} \rightarrow z_{isobar} = \frac{\omega^2}{2g} r^2 + C_1$$

Equation of the free surface

$$z_s = h_0 - \frac{\omega^2}{4g}\left(R^2 - 2r^2\right)$$

Examples of Archimedes Principle

The Golden Crown of Hiero II, King of Syracuse



- Archimedes, 287-212 B.C.
- Hiero, 306-215 B.C.
- Hiero learned of a rumor where the goldsmith replaced some of the gold in his crown with silver. Hiero asked Archimedes to determine whether the crown was pure gold.
- Archimedes had to develop a nondestructive testing method

The Golden Crown of Hiero II, King of Syracuse

- The weight of the crown and nugget are the same in air: $W_c = \rho_c V_c = W_n = \rho_n V_n$.
- If the crown is pure gold, $\rho_c=\rho_n$ which means that the volumes must be the same, $V_c=V_n$.
- In water, the buoyancy force is $B=\rho_{H2O}V$.
- If the scale becomes unbalanced, this implies that the $V_c \neq V_n$, which in turn means that the $\rho_c \neq \rho_n$
- Goldsmith was shown to be a fraud!